

# T5LH

- High lead: Lead 20
- Origin at non-motor side
- Controller: 100V / 200V



## Ordering method

### T5LH

Model	Lead designation	Brake	Origin position change	Grease type	Stroke	Cable length
	20: 20mm 12: 12mm 6: 6mm	No entry: No brakes BK: Brakes provided	None: Standard Z: Non-motor side	None: Standard GC: Clean	50 to 800 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

### TSX

Positioner	Driver: Power-supply voltage / Power capacity	LCD monitor	I/O selection	Battery
TS-X	105: 100V/100W or less 205: 200V/100W or less	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ GW: No I/O board	B: With battery (Absolute) N: None (Incremental)

### SR1-X

Controller	Driver: Power capacity	Usable for CE	I/O selection	Battery
05	05: 100W or less	No entry: Standard E: CE marking	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

### RDV-X

Driver	Power-supply voltage	Driver: Power capacity
2	Z: AC200V	05: 100W or less

- Note 1. The model with a lead of 20mm cannot select specifications with brake (flexible specifications).  
 Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.510 for details on robot cable.  
 Note 3. See P.446 for DIN rail mounting bracket.  
 Note 4. Select this selection when using the gateway function. For details, see P.439.

## Specifications

AC servo motor output (W)	30
Repeatability (mm)	+/-0.02
Deceleration mechanism	Ball screw $\phi$ 12 (Class C10)
Ball screw lead (mm)	20 12 6
Maximum speed (mm/sec)	1200 800 400
Maximum payload (kg)	Horizontal: 3 5 9 Vertical: - 1.2 2.4
Rated thrust (N)	19 32 64
Stroke (mm)	50 to 800 (50mm pitch)
Overall length (mm)	Horizontal: Stroke+201.5 Vertical: Stroke+239.5
Maximum dimensions of cross section of main unit (mm)	W55xH52
Cable length (m)	Standard: 3.5 / Option: 5,10
Linear guide type	2 rows of gothic arch grooves x 1 rail
Position detector	Resolvers
Resolution (Pulse/rotation)	16384

- Note 1. Positioning repeatability in one direction.  
 Note 2. When the stroke is longer than 600mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.  
 Note 3. Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

## Allowable overhang

	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)			Vertical installation (Unit: mm)		
	A	B	C	A	B	C	A	C	
Lead 20	1kg: 967	324	598	1kg: 551	304	925	1.2kg: 240	239	
Lead 12	3kg: 429	104	226	3kg: 185	89	378	2.4kg: 109	110	
Lead 6	2kg: 916	159	398	2kg: 347	141	800			
	5kg: 436	60	152	5kg: 119	44	355			
	3kg: 1194	105	294	3kg: 259	87	950			
	9kg: 624	31	89	9kg: 50	15	385			

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.  
 Note. Service life is calculated for 600mm stroke models.

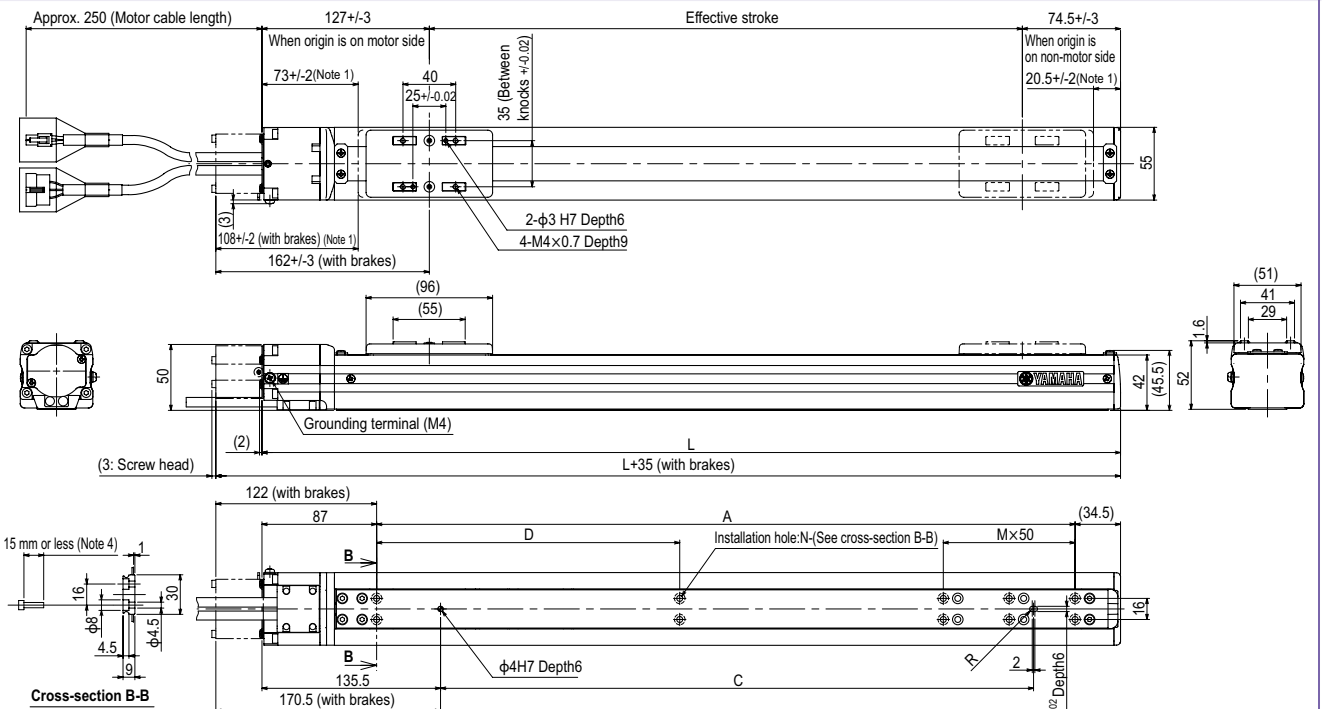
## Static loading moment

(Unit: N·m)		
MY	MP	MR
30	34	40

## Controller

Controller	Operation method
SR1-X05	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX221/222	
RCX240/340	
TS-X105	I/O point trace / Remote command
TS-X205	
RDV-X205	Pulse train control

## T5LH



Effective stroke	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
	L	251.5	301.5	351.5	401.5	451.5	501.5	551.5	601.5	651.5	701.5	751.5	801.5	851.5	901.5	951.5
A	130	180	230	280	330	380	430	480	530	580	630	680	730	780	830	880
C	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800
D	-	-	-	-	-	230	230	230	230	230	230	230	230	230	230	230
M	0	1	2	3	4	5	0	1	2	3	4	5	6	7	8	9
N	4	6	8	10	12	14	6	8	10	12	14	16	18	20	22	24
Weight (kg)	1.7	1.8	2.0	2.2	2.3	2.5	2.7	2.8	3.0	3.2	3.3	3.5	3.7	3.8	4.0	4.2
Maximum speed for each stroke (mm/sec)	Lead 20	1200														
	Lead 12	800														
	Lead 6	400														
	Speed setting	80% 70% 60% 55%														

- Note 1. Distance from both ends to the mechanical stopper.  
 Note 2. Minimum bend radius of motor cable is R30.  
 Note 3. Weight of models with no brake. The weight of brake-attached models is 0.2 kg heavier than the models with no brake shown in the table.  
 Note 4. The under-head length of the hex socket-head bolt (M4x0.7) to be used for the installation work is 15mm or less.  
 Note 5. When the stroke is longer than 600mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.  
 Note 6. External view of T5LH is identical to T5L.

APPLICATION  
 TRANSERO  
 FLIP-X  
 PHASER  
 X-X  
 Y-X  
 YP-X  
 CLEAN  
 CONTROLLER INFORMATION  
 T type  
 F type  
 GF type  
 N type  
 BR type