

NXY-W 4 axes



- Arm type
- Cable carrier
- Double Y axes specifications

Ordering method

NXY - C - WA1

Model	Cable	Combination	X-axis stroke	Y-axis stroke	Cable
			25 to 175cm	15 to 65cm ^{Note 1}	3L: 3.5m 5L: 5m 10L: 10m

Note 1. When the Y-axis stroke is different between the right and left, it will be an order-made.
 Note 2. Reference of special order: 2 units of RCX222

RCX340-4

Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery

Specify various controller setting items. RCX340 ▶ **P.494**

RCX240

Controller ^{Note 2}	CE Marking	Regenerative unit	Expansion I/O	Network option	IVY System	Gripper	Battery

Specify various controller setting items. RCX240/RCX240S ▶ **P.481**

Specification

	X-axis	Y-axis ^{Note 1}
Axis construction ^{Note 2}	N15D	F14
AC servo motor output (W)	400	100
Repeatability ^{Note 3} (mm)	+/-0.01	+/-0.01
Drive system	Ball screw (Class C7) ϕ 15	Ball screw (Class C7) ϕ 15
Ball screw lead (Deceleration ratio) (mm)	20	20
Maximum speed (mm/sec)	1200	1200
Moving range (mm)	250 to 1750	150 to 650
Robot cable length (m)	Standard: 3.5 Option: 5, 10	

Note 1. The same two Y axes are installed and they have same specifications. If axes of individually different stroke are desired, it will be an order-made. In that case, consult YAMAHA.
 Note 2. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots.
 Note 3. Positioning repeatability in one direction.

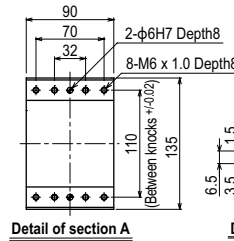
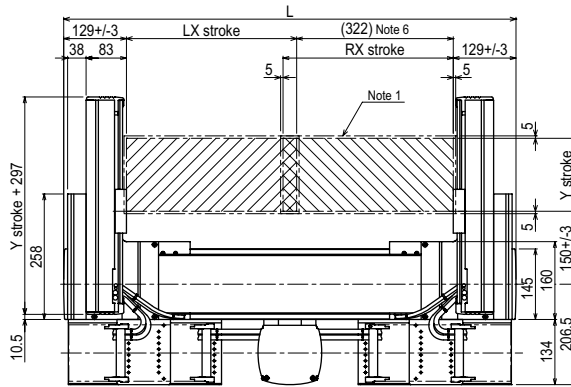
Maximum payload (kg)

Y stroke (mm)	XY 2 axes
150	25
250	21
350	18
450	16
550	13
650	11

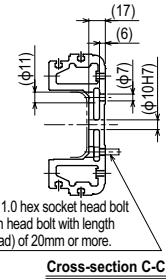
Controller

Controller	Operation method
RCX340	Programming / I/O point trace / Remote command / Operation using RS-232C communication
RCX240-R	

NXY-W 4 axes WA1

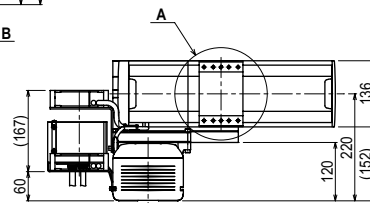
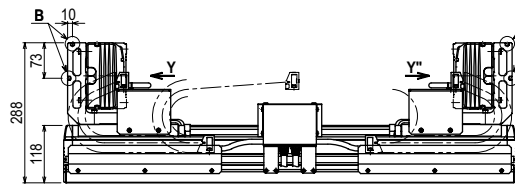


Detail of section B

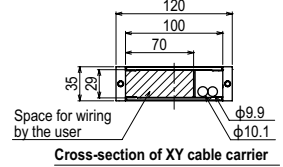


Use M6 x 1.0 hex socket head bolt with length head bolt with length (under head) of 20mm or more.

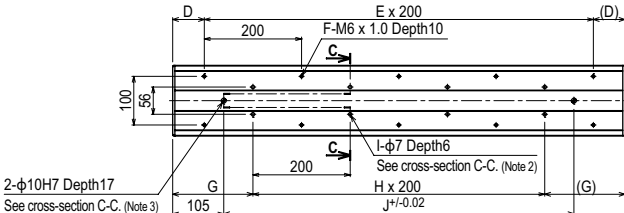
Cross-section C-C



VIEW Y (Y'' is symmetrical with this drawing.)



Cross-section of XY cable carrier



X stroke	250	350	450	550	650	750	850	950	1050	1150	1250	1350	1450	1550	1650	1750
L	830	930	1030	1130	1230	1330	1430	1530	1630	1730	1830	1930	2030	2130	2230	2330
D	15	65	15	65	15	65	15	65	15	65	15	65	15	65	15	65
E	4	4	5	5	6	6	7	7	8	8	9	9	10	10	11	11
F	10	10	12	12	14	14	16	16	18	18	20	20	22	22	24	24
G	115	165	115	165	115	165	115	165	115	165	115	165	115	165	115	165
H	3	3	4	4	5	5	6	6	7	7	8	8	9	9	10	10
I	8	8	10	10	12	12	14	14	16	16	18	18	20	20	22	22
J	620	720	820	920	1020	1120	1220	1320	1420	1520	1620	1720	1820	1920	2020	2120
Y stroke	150	250	350	450	550	650										

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
 Note 2. When using ϕ 7 holes for installation, you must not use a washer, spring washer, etc. in the main unit.
 Note 3. When using a ϕ 10H7 hole, make sure that the pin does not go into deeper than as shown in the drawing.
 Note 4. Use M4 tap of the box next to X axis for the user grounding terminal.
 Note 5. The M4 taps at both ends of the cable carriage can be used for fixing cables.
 Note 6. Minimum dimension between LX and RX sliders.