



● Pole type ● Whipover ● Z-axis: Clamped table / moving base type (200W) for Pole type

### Ordering method

**HXYx - S - P1**

Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable	Controller / Number of controllable axes	Safety standard	Option A (OP.A)	Option B (OP.B)	Option C (OP.C)	Option D (OP.D)	Option E (OP.E)	Absolute battery
			25 to 85cm	25 to 85cm	ZPHL ZPHR	25 to 65cm	3L: 3.5m 5L: 5m 10L: 10m	<b>RCX340-3</b>							

Specify various controller setting items. RCX340 ▶ **P494**

Controller	CE Marking	Regenerative unit	Expansion I/O	Network option	IVY System	Gripper	Battery
<b>RCX240</b>		<b>R</b>					<b>BB</b>

Specify various controller setting items. RCX240/RCX240S ▶ **P481**

### Specification

	X-axis	Y-axis	Z-axis
<b>Axial construction</b> <sup>Note 1</sup>	F20	F20-BK	F14H
<b>AC servo motor output (W)</b>	600	600	200
<b>Repeatability</b> <sup>Note 2</sup> (mm)	+/-0.01	+/-0.01	+/-0.01
<b>Drive system</b>	Ball screw (Class C7)	Ball screw (Class C7)	Ball screw (Class C7)
<b>Ball screw lead (Deceleration ratio) (mm)</b>	20	10	20
<b>Maximum speed</b> <sup>Note 3</sup> (mm/sec)	1200	600	1200
<b>Moving range (mm)</b>	250 to 850	250 to 850	250 to 650
<b>Robot cable length (m)</b>	Standard: 3.5 Option: 5,10		

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots.  
 Note 2. Positioning repeatability in one direction.  
 Note 3. The total of the X and Y strokes should be 1100mm or less and that of the Y and Z strokes should be 1200mm or less.  
 Note 4. When the X-axis/Y-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

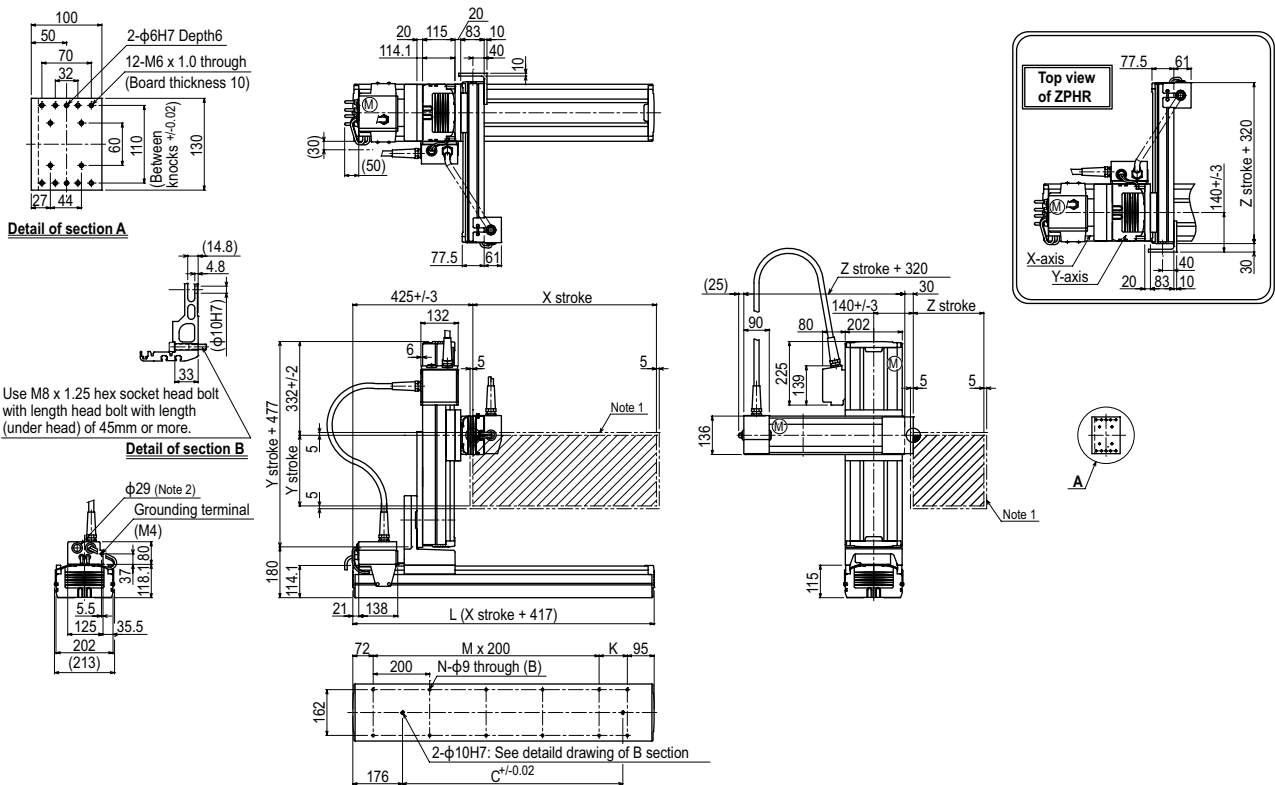
### Maximum payload (kg)

Y stroke (mm)	Z stroke (mm)
250 to 850	15

### Controller

Controller	Operation method
RCX340 RCX240-R	Programming / I/O point trace / Remote command / Operation using RS-232C communication

### HXYx 3 axes / ZPHL (P1)



X stroke <sup>Note 4</sup>	250	350	450	550	650	750	850
	L	667	767	867	967	1067	1167
K	100	200	100	200	100	200	100
D	420	420	600	600	780	780	960
M	2	2	3	3	4	4	5
N	8	8	10	10	12	12	14

Y stroke <sup>Note 4</sup>	250	350	450	550	650	750	850

Z stroke	250	350	450	550	650

Maximum speed for each stroke (mm/sec) <sup>Note 5</sup>	X-axis	1200	960
	Y-axis	600	480
	Speed setting	-	80%

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.  
 Note 2. User cable extraction port.  
 Note 3. This figure shows the combination for ZPHL. For the combination for ZPHR, see the top view in the figure.

Note 4. The total of the X and Y strokes should be 1100mm or less and that of the Y and Z strokes should be 1200mm or less.  
 Note 5. When the X-axis/Y-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

APPLICATION  
 TRANSERO  
 FLIP-X  
 PHASER  
 XX-X  
 YK-X  
 YP-X  
 CLEAN  
 CONTROLLER INFORMATION  
 Arm type  
 Gantry type  
 Moving arm type  
 Pole type  
 XZ type