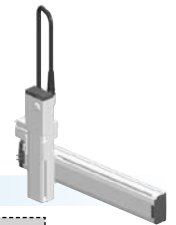


# SXYx 2 axes / ZF

- XZ type**
- Whipover**
- Z-axis: clamped base / moving table type (100W)**



## Ordering method

<b>SXYx - S</b>			<b>ZF</b>			<b>RCX222</b>				
Model	Cable	Combination	X-axis stroke	ZR-axis	Z-axis stroke	Cable	Controller	Usable for CE	Input/Output selection 1	Input/Output selection 2
		F1 F3	15 to 85cm		15 to 35cm	3L: 3.5m 5L: 5m 10L: 10m	RCX222	No entry: Standard E: CE marking	N: NPN <sup>Note 1</sup> P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS EN: Ethernet <sup>Note 2</sup> YC: YC-Link <sup>Note 2</sup>	No entry: None Nt: OPDIO24/16 (NPN) <sup>Note 1</sup> Pt: OPDIO24/17 (PNP) EN: Ethernet <sup>Note 3</sup>

Note 1. NPN cannot be selected if using CE marking.  
 Note 2. Available only for the master. See P.54 for details on YC-Link system.  
 Note 3. Only when CC or DN or PB was selected for I/O select 1 above. EN can be selected in I/O select 2.

## Specification

	X-axis	Z-axis
Axis construction <sup>Note 1</sup>	F14	F10-BK
AC servo motor output (W)	100	100
Repeatability <sup>Note 2</sup> (mm)	+/-0.01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	10
Maximum speed <sup>Note 3</sup> (mm/sec)	1200	600
Moving range (mm)	150 to 850	150 to 350
Robot cable length (m)	Standard: 3.5 Option: 5,10	

Note 1. Use caution that the flange machining (installation holes, tap holes) differs from single-axis robots.  
 Note 2. Positioning repeatability in one direction.  
 Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.

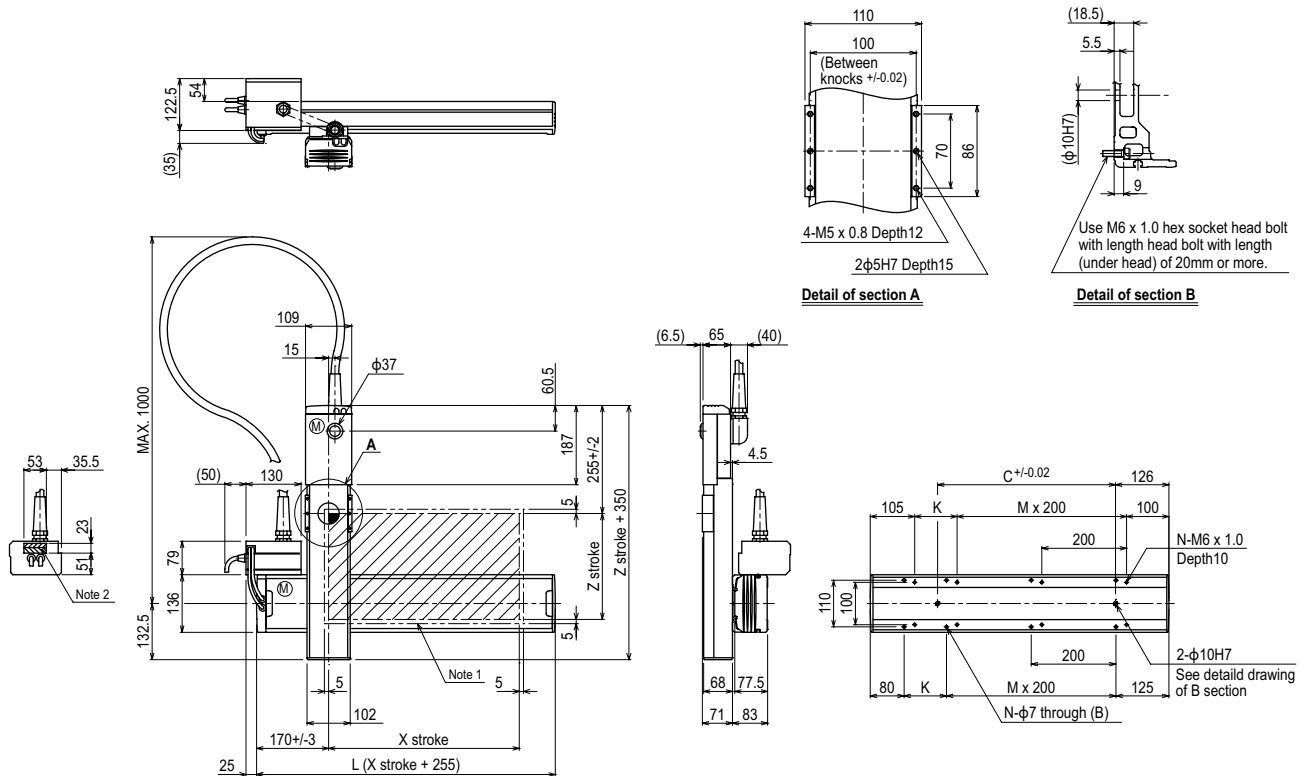
## Maximum payload (kg)

X stroke (mm)	Z stroke (mm)
150 to 850	10

## Controller

Controller	Operation method
RCX222	Programming / I/O point trace / Remote command / Operation using RS-232C communication

## SXYx 2 axes / ZF (F1)



X stroke	150	250	350	450	550	650	750	850
L	405	505	605	705	805	905	1005	1105
K	200	100	200	100	200	100	200	100
C	240	240	420	420	600	600	780	780
M	0	1	1	2	2	3	3	4
N	4	6	6	8	8	10	10	12
Z stroke	150	250	350					
Maximum speed for each stroke (mm/sec) <sup>Note 3</sup>	X-axis		1200			960		780
Speed setting			-			80%		65%

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.  
 Note 2. The shaded position indicates a user cable extraction port.

Note 3. When the X-axis stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.

APPLICATION  
 TRANSERO  
 FLIP-X  
 PHASER  
 XY-X  
 YK-X  
 YP-X  
 CLEAN  
 CONTROLLER  
 INFORMATION  
 Arm type  
 Gantry type  
 Moving arm type  
 Pole type  
 XZ type