

C14H

● Origin on the non-motor side is selectable: Lead 20 • 10



Ordering method

C14H

Model	Lead	Brake	Option	Stroke	Cable length
	20: 20mm 10: 10mm 5: 5mm	No entry: With no brake BK: With brake	Origin position change None: Standard Z: Non-motor side	150 to 1050 (50mm pitch)	3L: 3.5m 5L: 5m 10L: 10m 3K/5K/10K (Flexible cable)

TSX

Positioner	Driver: Power-supply voltage / Power capacity	Regenerative unit	LCD monitor	I/O selection	Battery
TS-X	110: 100V/200W 210: 200V/200W	No entry: None R: With RGT	No entry: None L: With LCD	NP: NPN PN: PNP CC: CC-Link DN: DeviceNet™ EP: EtherNet/IP™ PT: PROFINET GW: No I/O board	B: With battery (Absolute) N: None (Incremental)

SR1-X **10**

Controller	Driver: Power capacity	Usable for CE	Regenerative unit	I/O selection	Battery
	10: 200W	No entry: Standard E: CE marking	No entry: None R: With RG1	N: NPN P: PNP CC: CC-Link DN: DeviceNet™ PB: PROFIBUS	B: With battery (Absolute) N: None (Incremental)

RDV-X **2** **10** **RBR1**

Driver	Power-supply voltage	Driver: Power capacity	Regenerative unit
	2: AC200V	10: 200W or less	

Note 1. If selecting 5mm lead specifications then the origin point cannot be changed to the non-motor side.
 Note 2. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable. See P.594 for details on robot cable.
 Note 3. See P.498 for DIN rail mounting bracket.
 Note 4. Select this selection when using the gateway function. For details, see P.60.

Basic specifications

AC servo motor output (W)	200
Repeatability (mm)	+/-0.01
Deceleration mechanism	Ball screw (Class C7)
Ball screw lead (mm)	20 10 5
Maximum speed (mm/sec)	1000 500 250
Maximum payload (kg)	Horizontal 40 80 100 Vertical 8 20 30
Rated thrust (N)	170 341 683
Stroke (mm)	150 to 1050 (50mm pitch)
Overall length (mm)	Horizontal Stroke+349 Vertical Stroke+379
Maximum outside dimension of body cross-section (mm)	W136 x H96
Cable length (m)	Standard: 3.5 / Option: 5, 10
Degree of cleanliness	CLASS 10
Intake air (Nl/min)	30 to 90

Note 1. Positioning repeatability in one direction.
 Note 2. When the stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
 Note 3. Per 1cf (0.1um base), when suction blower is used.
 Note 4. The necessary intake amount varies depending on the use conditions and environment.

Allowable overhang

Lead	Horizontal installation (Unit: mm)			Wall installation (Unit: mm)			Vertical installation (Unit: mm)		
	A	B	C	A	B	C	A	B	C
Lead 20	10kg	2247	1675	987	1210	1678	4kg	2400	2008
	20kg	1397	855	528	497	548	6kg	1687	1358
	40kg	1037	445	318	247	217	8kg	1287	1033
Lead 10	30kg	1937	583	478	402	328	10kg	1347	1088
	50kg	1637	364	323	227	152	15kg	887	718
	80kg	1717	242	235	119	74	20kg	657	538
Lead 5	60kg	2443	311	313	197	108	20kg	747	608
	80kg	2193	242	250	127	53	25kg	663	484
	100kg	2000	202	213	85	20	30kg	491	396

Note. Distance from center of slider top to center of gravity of object being carried at a guide service life of 10,000 km.

Static loading moment

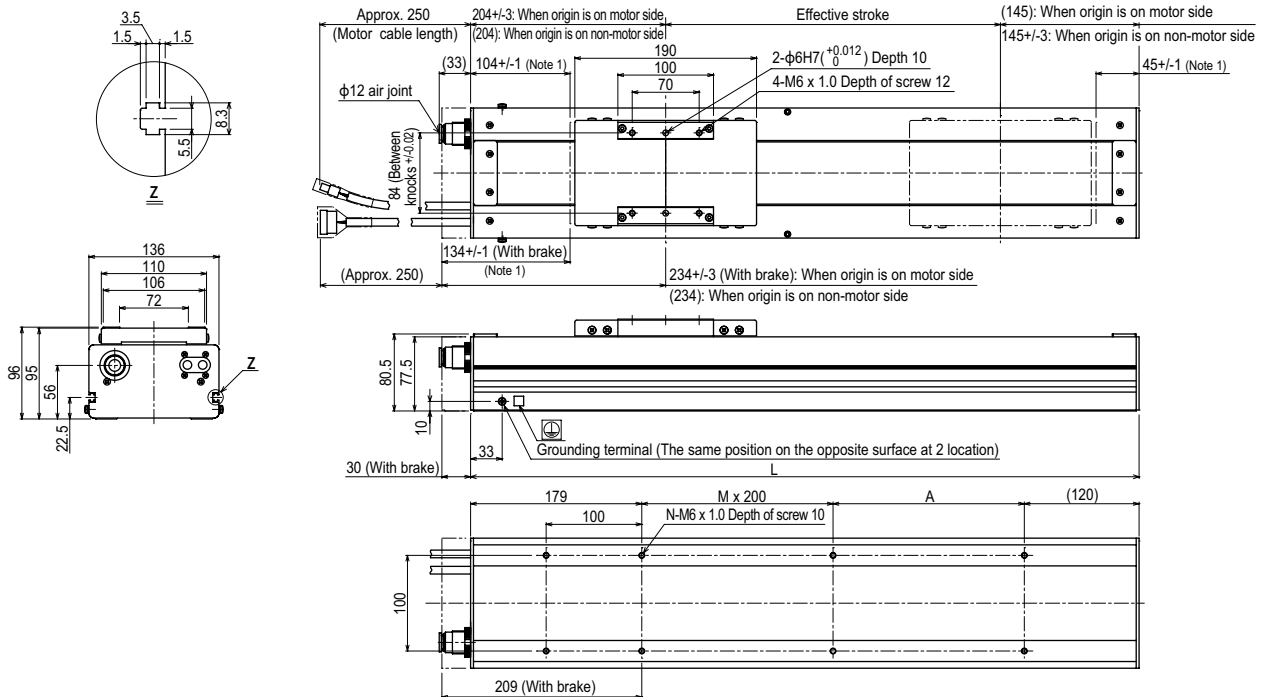
(Unit: N·m)		
MY	MP	MR
293	294	258

Controller

Controller	Operation method
SR1-X10	Programming / I/O point trace / Remote command
RCX221/222	Operation using RS-232C communication
RCX240/340	I/O point trace / Remote command
TS-X110	Pulse train control
TS-X210	
RDV-X210-RBR1	

Note. Regenerative unit is required when used vertically.

C14H



Effective stroke	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000	1050
	L	499	549	599	649	699	749	799	849	899	949	999	1049	1099	1149	1199	1249	1299	1349
A	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100	150	200	50	100
M	0	1	1	1	1	2	2	2	2	3	3	3	3	4	4	4	4	5	5
N	6	8	8	8	8	10	10	10	10	12	12	12	12	14	14	14	14	16	16
Weight (kg)	10.7	11.4	12.0	12.7	13.2	13.9	14.5	15.2	15.8	16.5	17.0	17.7	18.3	19.0	19.6	20.3	20.8	21.5	22.1
Maximum speed (mm/sec)	Lead 20	1000																	
	Lead 10	500																	
	Lead 5	250																	
	Speed setting	95% 95% 75% 75% 60% 60% 50%																	

Note 1. Stop positions are determined by the mechanical stoppers at both ends.
 Note 2. Minimum bend radius of motor cable is R50.
 Note 3. Weight of models with no brake. The weight of brake-attached models is 0.4 kg heavier than the models with no brake shown in the table.

Note 4. When the stroke is longer than 750mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.